



neptronic®

EVCB14NxT4X

Modbus Communication Module User Guide



EVCB14NIT0X	(0 TRIACS / pressure independent / external motor)
EVCB14NIT4X	(4 TRIACS / pressure independent / external motor)
EVCB14NDT4X	(4 TRIACS / pressure dependent / external motor)





Introduction

The EVCB14NxT4X Modbus Communication Module User Guide provides information for using Neptronic® communication feature. The controller uses Modbus communication protocol over serial line in the RTU mode and provides a Modbus network interface between client devices and Neptronic EVCB14NxT4X devices.

The EVCB14NxT4X Modbus Guide assumes that you are familiar with Modbus terminology.

The following are the requirements for Modbus:

- **Data Model.** The EVCB Modbus server data model uses only the Holding Registers table.
- **Function Codes.** The EVCB Modbus server supports a limited function codes subset comprising:
 - Read Holding Registers (0x03)
 - Write Single Register (0x06)
 - Write Multiple Registers (0x10)
- **Exception Responses.** The EVCB Modbus server supports the following exception codes:
 - Illegal data address
 - Illegal data value
 - Slave device busy
- **Serial Line.** The EVCB Modbus over serial line uses RTU transmission mode over a two-wire configuration RS485 (EIA/TIA-485 standard) physical layer.
 - The physical layer can use fixed baud rate selection or automatic baud rate detection (default) as per the **Modbus Auto Baud Rate** device menu item or holding register index 1.
 - The supported baud rates are 9600, 19200, 38400, and 57600.
 - The physical layer also supports variable parity control and stop bit configuration as per the **Modbus Comport Config** device menu item or holding register index 2.
 - In auto baud rate configuration, if the device detects only consecutive bad frames (2 or more) for one second with any given baud rate, it will reinitialize itself to the next baud rate.
- **Addressing.** The EVCB device only answers at the following address:
 - The device's unique address (1 to 246) that can be set through the device menu or through holding register index 0.

Holding Registers Table

Table Glossary

Name	Description	Name	Description
W	Writable Register	ASCII	For registers containing ASCII (8-bit) characters
RO	Read Only Register	MSB	Most Significant Byte
Unsigned	For range of values from 0 to 65,535, unless otherwise specified	LSB	Least Significant Byte
Signed	For range of values from -32,768 to 32,767, unless otherwise specified	MSW	Most Significant Word
Bit String	For registers with multiple values using bit mask (example, flags)	LSW	Least Significant Word

Holding Register Table

Protocol Address	Convention Notation	Description	Data Type	Range	Writable
0	40001	Modbus Address and Product Type.	Unsigned	MSB = Product type (e.g. 111 for EVCB) LSB = Modbus Address (e.g. 1-246)	W
1	40002	MSTP Baud Rate.	Unsigned <i>Scale 100</i>	0, 9600, 19200, 38400, or 57600 0 = Auto Baud Rate Detection <i>Value/100 (e.g. 38400 baud = 384)</i>	W
2	40003	Modbus Slave Communication Port Configuration.	Unsigned	1= No parity, 2 Stop bits 2= Even parity, 1 stop bit 3= Odd parity, 1 stop bit	W
3	40004	Product Name (characters 8 & 7).	ASCII	1 to 65,535 char 8: 0x53 = S char 7: 0x00 =	W
4	40005	Product Name (characters 6 & 5).	ASCII	1 to 65,535 char 6: 0x49 = I char 5: 0x34 = 4	W
5	40006	Product Name (characters 4 & 3).	ASCII	1 to 65,535 char 4: 0x42 = B char 3: 0x4E = N	W
6	40007	Product Name (characters 2 & 1).	ASCII	1 to 65,535 char 2: 0x45 = E char 1: 0x56 = V	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
7	40008	Product actual firmware version.	Unsigned	1 to 65535 (e.g. 508)	RO
8	40009	Product actual EEPROM version.	Unsigned	1 to 65535 (e.g. 203)	RO
9	40010	System Status 1.	Bit String	[B0 – B11]: Reserved B12: CO2 alarm <i>0 = Normal; 1 = Alarm</i> B13: Pressure mode (actual status) <i>0 = Independent; 1 = Dependent</i> B14: Air Flow <i>0 = Normal; 1 = Error</i>	RO
10	40011	System Status 2.	Bit String	[B0-B11, B13-B14]: Reserved B12: Alarm override <i>0 = Normal; 1 = Alarm</i>	RO
11	40012	Internal Temperature.	Unsigned <i>Scale 100</i>	0 to 5000 <i>Value x 100 (e.g. 23°C = 2300)</i>	RO
12	40013	External Temperature.	Signed <i>Scale 100</i>	-4000 to 10000 <i>Value x 100 (e.g. 18°C = 1800)</i>	RO
13	40014	Change Over Temperature.	Signed <i>Scale 100</i>	-4000 to 10000 <i>Value x 100 (e.g. 18°C = 1800)</i>	RO
14	40015	Internal humidity, reading of the integrated humidity sensor of TRLH or TRLGH/TDU (models with humidity sensor). If not available, the value will be fixed to 0x7FFF (32767).	Unsigned <i>Scale 10</i>	0 to 1000 <i>Value x 10 (e.g. 45%RH = 450)</i>	RO
15	40016	Input 3 reading, pressure sensor value. (Not available on EVCB14NDT4X models)	Unsigned	0 to 2500 <i>Value x 10 (e.g. 10 Pa = 100)</i>	RO
16	40017	Analog input 1 value.	Unsigned <i>Scale 100</i>	0 to 1000 <i>Value x 100 (e.g. 2 mV = 200)</i>	RO
17	40018	Analog Input 2 value.	Unsigned <i>Scale 100</i>	0 to 1000 <i>Value x 100 (e.g. 3 mV = 300)</i>	RO



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
18	40019	CO2 value in ppm: If using AI1 or AI2 and CO2 is set in Analog mode, the reading is from the external sensor.	Unsigned Scale 100	100 to reg 40098 Value x 100 (e.g. 5 ppm = 500)	RO
19	40020	Air supply temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO
20	40021	Control temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 25°C = 2500)	W
21	40022	Heating demand for heating ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
22	40023	Cooling demand for cooling ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
23	40024	Temperature offset applied on internal temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
24	40025	Temperature offset applied on external temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
25	40026	Temperature setpoint used during the occupancy period of the day.	Unsigned Scale 10	Range: 40027 to 40028 Value x 10 (e.g. 20°C = 200)	W
26	40027	Minimum temperature setpoint used during the day.	Unsigned Scale 10	Range: 100 to 40028 Value x 10 (e.g. 10°C = 100)	W
27	40028	Maximum temperature setpoint used during the day.	Unsigned Scale 10	Range: 40027 to 400 Value x 10 (e.g. 40°C = 400)	W
28	40029	Cooling setpoint during No Occupancy/Night Set Back.	Unsigned Scale 10	Range: 40030 to 400 Value x 10 (e.g. 22°C = 220)	W
29	40030	Heating setpoint during No Occupancy/Night Set Back.	Unsigned Scale 10	Range: 100 to 40029 Value x 10 (e.g. 16°C = 160)	W
30	40031	Cooling demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.3°C = 3)	W
31	40032	Heating demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.3°C = 3)	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
32	40033	Cooling dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W
33	40034	Heating dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W
34	40035	Changeover temperature setpoint.	Unsigned Scale 10	100 to 400 Value x 10 (e.g. 12°C = 120)	W
35	40036	Night setback override delay in minutes.	Unsigned	0 to 180 minutes	W
36	40037	Integral time factor for heating in seconds.	Unsigned	0 to 250 seconds	W
37	40038	Cooling anti-cycle delay: delay in minutes before activating or reactivating the cooling contact.	Unsigned	0 to 15 minutes	W
38	40039	Floating time 1: Indicates the time in seconds required by the actuator to complete a 90° run.	Unsigned	15 to 250 seconds	W
39	40040	Occupancy Delay Mode in minutes.	Unsigned	0 to 180 minutes	W
40	40041	Cooling demand for cooling ramp 2.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	RO
41	40042	Proportional band for cooling ramp 2.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
42	40043	Dead band for cooling ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
43	40044	Heating demand for heating ramp 2.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	W
44	40045	Proportional band for heating ramp 2.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
45	40046	Dead band for heating ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
46	40047	Changeover demand for the VAV box.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	RO



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
47	40048	Changeover proportional band: the range in which the controller modulates the cooling and heating output from 0 to 100%.	Unsigned Scale 10	5 to 50 <i>Value x 10 (e.g. 0.2°C = 2)</i>	W
48	40049	Changeover deadband: the range at which the controller takes no action when the temperature is above or below the setpoint.	Unsigned Scale 10	0 to 50 <i>Value x 10 (e.g. 0.2°C = 2)</i>	W
49	40050	AO1 min Vdc: minimum voltage of analog output 1.	Unsigned Scale 10	Range: 0 to reg. 40052 <i>Value x 10 (e.g. 2 Volts = 20)</i>	W
50	40051	AO2 min Vdc: minimum voltage of analog output 2.	Unsigned Scale 10	Range: 0 to reg. 40053 <i>Value x 10 (e.g. 2 Volts = 20)</i>	W
51	40052	AO1 max Vdc: maximum voltage of analog output 1.	Unsigned Scale 10	Range: reg. 40050 to 100 <i>Value x 10 (e.g. 10 Volts = 100)</i>	W
52	40053	AO2 max Vdc: maximum voltage of analog output 2.	Unsigned Scale 10	Range: reg. 40051 to 100 <i>Value x 10 (e.g. 10 Volts = 100)</i>	W
* = The minimum and maximum voltages correspond to 0 to 100% demand. The minimum voltage is always applied to the output. The maximum voltage is applied when the demand reaches 100%. For reheat applications, we recommend leaving the minimum voltage at 0Vdc to avoid heating when the demand is 0%.					
53	40054	Time of numerical filter of delta pressure in seconds. (Not available on EVCB14NDT4X models)	Unsigned	1 to 10 seconds	W
54	40055	Factor of $V=K*\sqrt{dP}$, where $dP = 1$. (Not available on EVCB14NDT4X models)	Unsigned	Range: 100 to 9995 CFM	W
55	40056	Minimum air flow for cooling. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 or (12.7%) Kfac to reg 40057 CFM	W
56	40057	Maximum air flow for cooling. (Not available on EVCB14NDT4X models)	Unsigned	Range: reg 40056 to reg 40055 CFM	W
57	40058	Minimum air flow for heating. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 or (12.7%) Kfac to reg 40059 CFM	W
58	40059	Maximum air flow for heating. (Not available on EVCB14NDT4X models)	Unsigned	Range: reg 40058 to reg 40055 CFM	W
59	40060	<i>Reserved</i>			



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
60	40061	Actual air flow converted from delta pressure sensor. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 to reg 40055 CFM	RO
61	40062	Air flow calculated from system demand. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 to 9999 CFM	RO
62	40063	Configuration value for Air Flow Max used during airflow balancing sequence. Refer to EVCB-Airflow Balance Instructions. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 to 9999 CFM	W
63	40064	Analog output 1 value.	Unsigned Scale 10	Unit: Volt, Range: reg 40050 to reg 40052 Value x 10 (e.g. 5 Volts = 50)	W
64	40065	Analog output 2 value.	Unsigned Scale 10	Unit: Volt, Range: reg 40051 to reg 40053 Value x 10 (e.g. 5 Volts = 50)	W
65	40066	Percentage of demand to close TRIAC output 1.	Unsigned	15 to 80%	W
66	40067	Percentage of demand to close TRIAC output 2.	Unsigned	15 to 80%	W
67	40068	Percentage of demand to close TRIAC output 3.	Unsigned	15 to 80%	W
68	40069	Percentage of demand to close TRIAC output 4.	Unsigned	15 to 80%	W
69	40070	Percentage of demand to open TRIAC output 1.	Unsigned	0 to reg 40066-4%	W
70	40071	Percentage of demand to open TRIAC output 2.	Unsigned	0 to reg 40067-4%	W
71	40072	Percentage of demand to open TRIAC output 3.	Unsigned	0 to reg 40068-4%	W
72	40073	Percentage of demand to open TRIAC output 4.	Unsigned	0 to reg 40069-4%	W
73	40074	Integral time factor for cooling in seconds.	Unsigned	0 to 250 seconds	W
74	40075	Motor position.	Unsigned	0 to 100‰ (per mille)	RO
75	40076	Reserved			
76	40077	Reserved			
77	40078	Reserved			
78	40079	Reserved			



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
79	40080	<i>Reserved</i>			
80	40081	<i>Reserved</i>			
81	40082	Air flow offset calibration. Refer to EVCB-Airflow Balance Instructions. (Not available on EVCB14NDT4X models)	Signed	-500 to 500 CFM	W
82	40083	<i>Reserved</i>			
83	40084	<i>Reserved</i>			
84	40085	Configuration value for Air Flow Min used during airflow balancing sequence. Refer to EVCB-Airflow Balance Instructions. (Not available on EVCB14NDT4X models)	Unsigned	Range: 0 to 9999 CFM	W
85 to 95	40086 to 40096	<i>Reserved</i>			
96	40097	Network fallback timeout Present Value in minutes.	Unsigned	0 to 60 minutes	W
97	40098	<i>Reserved</i>			
98	40099	Maximum range of the CO2 sensor connected to AI1 or AI2.	Unsigned	100 to 5000 PPM	W
99	40100	Maximum concentration of CO2 before the EVC activates an alarm.	Unsigned	Range: 100 to the greater ppm value between 2000 and reg 40099	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
100	40101	System Option 1.	Bit String	<p>B3, B13-B14: Reserved</p> <p>B0: Tstat temperature units 0 = Celsius; 1 = Fahrenheit</p> <p>B1: Modbus temperature units 0 = Celsius; 1 = Fahrenheit</p> <p>B2: Temperature setpoint lock 0 = Unlocked; 1 = Locked</p> <p>B4: TO1/TO2 floating direction 0 = Direct; 1 = Reverse</p> <p>B5: TO3/TO4 floating direction 0 = Direct; 1 = Reverse</p> <p>B6: Onboard motor direction 0 = Direct; 1 = Reverse</p> <p>B7: Freeze protection 0 = Disabled; 1 = Enabled</p> <p>B8: User system off mode 0 = User can set Tstat to OFF 1 = User cannot set Tstat OFF</p> <p>B9: Keypad bottom left lock 0 = Unlocked; 1 = Locked</p> <p>B10: Keypad upper left lock 0 = Unlocked; 1 = Locked</p> <p>B11: Keypad arrows lock 0 = Unlocked; 1 = Locked</p> <p>B12: Program lock 0 = Unlocked; 1 = Locked</p> <p>B15: Schedule 0 = Disabled; 1 = Enabled</p>	W
101	40102	System Option 2.	Bit String	<p>B0-B1, B10, B12, B13, B15: Reserved</p> <p>B2: Auto baud rate detection 0 = Enabled; 1 = Disabled</p> <p>B3: Night setback mode 0 = Tstat ON; 1 = Tstat OFF</p> <p>B4: AO1 direction 0 = Direct; 1 = Reverse</p> <p>B5: AO2 direction 0 = Direct; 1 = Reverse</p> <p>B6: TO1 direction 0 = Direct; 1 = Reverse</p> <p>B7: TO2 direction 0 = Direct; 1 = Reverse</p> <p>B8: TO3 direction 0 = Direct; 1 = Reverse</p> <p>B9: TO4 direction 0 = Direct; 1 = Reverse</p> <p>B10: Display RH[®] 0 = No; 1 = Yes</p> <p>B11: Pressure mode select 0 = independent; 1 = dependent</p> <p>B14: DI 2 Contact 0: NO; 1: NC</p>	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
102	40103	Status value of the actual changeover control mode.	Unsigned	0 = Cooling, 1= Heating	RO
103	40104	System command status.	Unsigned	0 = No Command 1 = AirFlow 1 Balancing 4 = AirFlow 2 Balancing	W
104	40105	TO OnOff.	Unsigned	1 = TO1 OnOff 2 = TO2 OnOff 4 = TO3 OnOff 8 = TO4 OnOff	RO
105	40106	Occupancy or night setback mode commands.	Unsigned	1 = Locally 2 = Off 3 = Occupancy 4 = NoOccupancy 5 = Day 6 = Night	W
106	40107	Status of digital input 1.	Unsigned	0 = Open 1 = Close	RO
107	40108	Analog input 1 signal. (*Not available on EVCB14NDT4X models)	Unsigned	1 = OFF 2 = ETS (external temp) 3 = SENS (changeover sensor) 4 = NoCL (normally cool) 5 = NoHT (normally heat) 6 = STFL* (setpnt airflow 0-10Vdc) 7 = CO2 (carbon dioxide) 8 = AST (air supply temp sensor) 9 = mor (motor position)	W
108	40109	User System Control Mode.	Unsigned	1 = AUTO 2 = HEAT 3 = COOL 4 = OFF	W
109	40110	Sets the permissions or restrictions to change the system control mode by the user.	Unsigned	1 = AUTO 2 = HEAT 3 = COOL 4 = COOL-HEAT 5 = AUTO-LOCK	W
110	40111	Indicates the status of the Night Setback mode.	Unsigned	1 = Day 2 = Night 3 = Derogation	RO
111	40112	Configuration of DI1 mode. Night setback or no occupancy status.	Unsigned	1=Off 2= Occupancy NO 3= Occupancy NC 4= Night Set Back NO 5= Night Set Back NC	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
112	40113	Analog input 2 signal. (*Not available on EVCB14NDT4X models)	Unsigned	1 = OFF 2 = ETS (external temp) 3 = SENS (changeover sensor) 4 = NoCL (normally cool) 5 = NoHT (normally heat) 6 = STFL* (setpnt airflow 0-10Vdc) 7 = CO2 (carbon dioxide) 8 = AST (air supply temp sensor) 9 = mor (motor position)	W
113	40114	Occupancy status of the zone.	Unsigned	1 = No Occupancy 2 = Occupancy 3 = Derogation	RO
114	40115	AO1: Analog output 1 control ramp. (*Not available on EVCB14NDT4X models)	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = ArFL (airflow reading) 7 = CO2 (carbon dioxide) 8 = STFL* (setpnt airflow 0-10Vdc) 9 – 12 = reserved	W
115	40116	AO2: Analog output 2 control ramp. (*Not available on EVCB14NDT4X models)	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = ArFL (airflow reading) 7 = CO2 (carbon dioxide) 8 = STFL* (setpnt airflow 0-10Vdc) 9 – 12 = reserved	W
116	40117	TO1: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO1 based on demand.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = CO2 (carbon dioxide) 7 = STFL (setpnt airflow 0-10Vdc) 8 = COR (changeover ramp) 9 = CH1 (cool/heat 1) 10 = ANLG (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
117	40118	TO2: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO2 based on demand.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = CO2 (carbon dioxide) 7 = STFL (setpnt airflow 0-10Vdc) 8 = COR (changeover ramp) 9 = CH1 (cool/heat 1) 10 = ANLG (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
118	40119	TO3: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO3 based on demand.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = CO2 (carbon dioxide) 7 = STFL (setpnt airflow 0-10Vdc) 8 = COR (changeover ramp) 9 = CH1 (cool/heat 1) 10 = ANLG (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W



Protocol Address	Convention Notation	Description	Data Type	Range		Writable
119	40120	TO4: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO4 based on demand.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = CO2 (carbon dioxide)	7 = STFL (setpnt airflow 0-10Vdc) 8 = COR (changeover ramp) 9 = CH1 (cool/heat 1) 10 = ANLG (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
120	40121	TO1: Signal output type for TRIAC output 1.	Unsigned	3 = Pulsing 4 = On_Off 5 = Floating		W
121	40122	TO2: Signal output type for TRIAC output 2.	Unsigned	3 = Pulsing 4 = On_Off		W
122	40123	TO3: Signal output type for TRIAC output 3.	Unsigned	3 = Pulsing 4 = On_Off 5 = Floating		W
123	40124	TO4: Signal output type for TRIAC output 4.	Unsigned	3 = Pulsing 4 = On_Off		W
124	40125	Pressure independent output selection for VAV damper actuator. (Not available on EVCB14NDT4X models)	Unsigned	3 = Floating1 4 = Floating2 5 = Motor		W
125	40126	Motor ramp: Configuration of the ramp used to modulate the actuator based on demand. (*Not available on EVCB14NDT4X models)	Unsigned	2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2) 6 = Not Available	7 = STFL* (setpnt airflow 0-10Vdc) 8 = COR (changeover ramp) 9 = CH1 (cool/heat 1) 10 = ANLG (analog 0-10Vdc)	W
126	40127	Changeover control mode status that indicates the source of changeover values.	Unsigned	1 = Local 2 = Cooling 3 = Heating		W
127	40128	<i>Reserved</i>				
128	40129	<i>Reserved</i>				
129	40130	Configuration of DI2 mode.	Unsigned	1=Off 2=Override 3=OverHeat1	4=OverHeat2 5=OverHeatAll 6=ChangeOverNoCooling 7=ChangeOverNoHeating	W
130	40131	Selected temperature control source (in Programming mode).	Unsigned	1 = Internal Temperature 2 = External Temperature 3 = Remote Temperature	4 = Average Temperature 5 = Maximum Temperature	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
131	40132	Airflow balance mode, enter the balancing mode to adjust air flow factor. (Not available on EVCB14NDT4X models)	Unsigned	1 = Close 2 = Minimum Flow 3 = Maximum Flow 4 = Full Open	W
132	40133	<i>Reserved</i>			
133	40134	Configuration to set the motor position in night setback mode.	Unsigned	1 = Auto 2 = Open	W
134	40135	Digital input 2 delay in seconds.	Unsigned	0 to 3600 seconds	W
135	40136	Time in seconds required by the actuator to complete a 90° run.	Unsigned	15 to 420 seconds	W
136	40137	Minimum motor position in percentage of stroke for cooling.	Unsigned	0 to 100%	W
137	40138	Minimum motor position in percentage of stroke for heating.	Unsigned	0 to 100%	W
138	40139	Airflow Setpoint Hysteresis in percentage. (Not available on EVCB14NDT4X models)	Unsigned	0 to 100%	W
139	40140	Airflow Hysteresis in percentage. (Not available on EVCB14NDT4X models)	Unsigned	0 to 100%	W
140	40141	Airflow scale. (Not available on EVCB14NDT4X models)	Unsigned	1 = Scale1 2 = Scale10 3 = Scale100	W
141	40142	Airflow fault deadband in percentage. (Not available on EVCB14NDT4X models)	Unsigned	1 to 30%	W
142	40143	Airflow fault error in percentage. (Not available on EVCB14NDT4X models)	Unsigned	0 to 100%	W
143	40144	Airflow fault hysteresis in percentage. (Not available on EVCB14NDT4X models)	Unsigned	1 to 30%	W
144	40145	Airflow fault time. (Not available on EVCB14NDT4X models)	Unsigned	2 to 59 minutes	W
145	40146	CL_HT SwitchTimer, waiting time before switching between the heating and cooling modes.	Unsigned	0 to 120 minutes	W



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
146	40147	CL_HT SwitchTimerCount, countdown to indicate the swap between heating and cooling modes.	Unsigned	0 to 4,294,967,295 seconds	RO
147	40148	FloatingTO1/TO2, TRIAC output 1 or 2 when set to floating, indicates the floating signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
148	40149	FloatingTO3/TO4, TRIAC output 3 or 4 when set to floating, indicates the floating signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
149	40150	TO1 Pulsing, TRIAC output 1 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
150	40151	TO2 Pulsing, TRIAC output 2 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
151	40152	TO3 Pulsing, TRIAC output 3 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
152	40153	TO4 Pulsing, TRIAC output 4 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% <i>Value x 10 (e.g. 15% =150)</i>	RO
153	40154	Overheat status.	Unsigned	1 = OverHeatNormal 2 = OverHeat1 3 = OverHeat2 4 = OverHeatAll	RO
154	40155	Configuration to override the motor position.	Unsigned	1 = Auto 2 = Open 3 = Close 4 = AirFlowCoolMin 5 = AirFlowCoolMax	W
155	40156	Information displayed on the TRL/TDU.	Unsigned	1 = Temp Demand 2 = Setpoint Demand 3 = Temp 4 = Setpoint 5 = Off	W
156	40157	Status of digital input 2.	Unsigned	0 = Open 1 = Close	RO

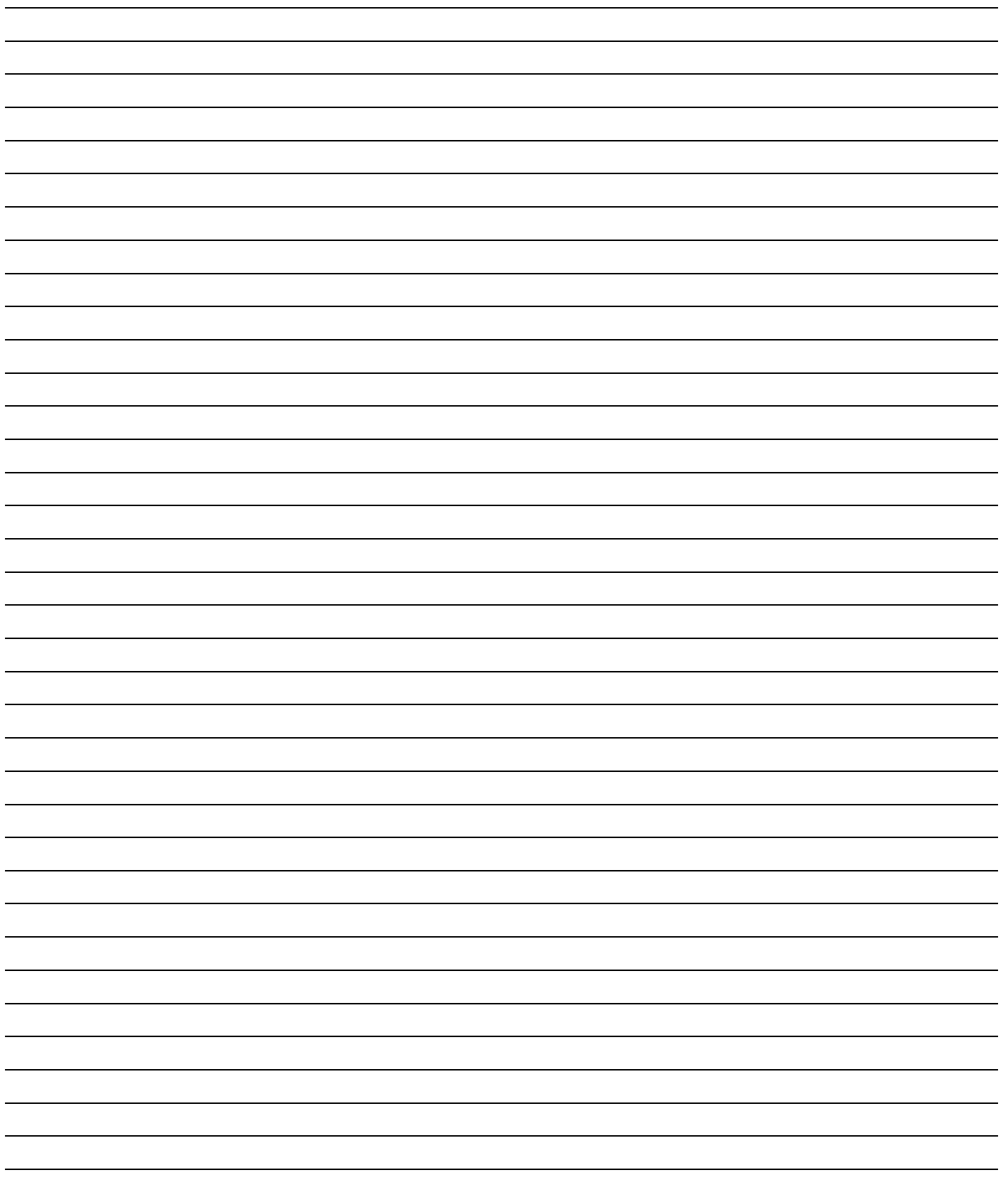


Protocol Address	Convention Notation	Description	Data Type	Range	Writable
157	40158	<i>Reserved</i>			
158	40159	Minimum voltage of the external actuator's control signal.	Unsigned Scale 100	Range: 0 to reg. 400160 Value x 100 (e.g. 2 Volts = 200)	W
159	40160	Maximum voltage of the external actuator's control signal.	Unsigned Scale 100	Range: reg. 400159 to 1000 Value x 100 (e.g. 10 Volts = 1000)	W
160	40161	Minimum voltage of the external actuator's feedback signal.	Unsigned Scale 100	Range: 0 to reg. 400162 Value x 100 (e.g. 2 Volts = 200)	W
161	40162	Maximum voltage of the external actuator's feedback signal.	Unsigned Scale 100	Range: reg. 400161 to 1000 Value x 100 (e.g. 10 Volts = 1000)	W
162	40163	System Options 3.	Bit String	B0-B1, B4-B6, B8, B11-B15: Reserved B2: CO₂ Display 0 = No; 1 = Yes B3: CO₂ Control Source 0 = Analog; 1 = TRLG B7: Occupancy Control Source 0 = BinaryInput1; 1 = InternSensor B9: Motor Position Control Temperature Fault 0 = Close; 1 = Full Open B10: CO₂ Control Mode 0 = Open; 1 = Control ramp	W
163	40164	<i>Reserved</i>			
164	40165	Internal CO ₂ , reading of the integrated CO ₂ sensor of TRLG or TRLGH/TDU (models with humidity sensor). If not available, the value will be fixed to 0x7FFF (32767).	Unsigned	0 to 2000 ppm	RO
165	40166	Internal light sensor reading in Luxes.	Unsigned	0 to 16000 Luxes	RO
166	40167	Internal VOC sensor reading in ppb.	Unsigned	0 to 60000 ppb	RO
167	40168	Internal PIR sensor reading.	Unsigned	0 = NoOccupancy 1 = Occupancy	RO



Protocol Address	Convention Notation	Description	Data Type	Range	Writable
168	40169	Occupancy minimum time in minutes.	Unsigned Scale 1	Range: 0 to 240 Value x 1 (e.g. 10 minutes = 10)	W
169	40170	Configuration value of the minimum position in cooling/heating mode in %.	Unsigned	0 to 100 %	W
170	40171	Control Setpoint.	Unsigned Scale 1	10 to 40 Value x 1 (e.g. 30°C = 30)	RO
171	40172	CO2 ramp proportional band.	Unsigned Scale 1	50 to 250 ppm Value x 1 (e.g. 50ppm = 50)	W
172	40173	CO2 ramp dead band.	Unsigned Scale 1	10 to 50 ppm Value x 1 (e.g. 50ppm = 50)	W
173	40174	Temperature sensor combination.	Unsigned	1 = TSTAT+AI1 2 = TSTAT+AI2 3 = TSTAT+AI1+AI2 4 = AI1+AI2	W
174	40175	Average temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO
175	40176	Maximum temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO
176	40177	External sensor value of analog input 2.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO

[illegible]





neptronic®

400 Lebeau blvd, Montreal, Qc, H4N 1R6, Canada

neptronic.com

Toll free in North America: 1-800-361-2308

Tel.: (514) 333-1433

Fax: (514) 333-3163

Customer service fax: (514) 333-1091

Monday to Friday: 8:00am to 5:00pm (Eastern time)